

Our gripper can directly connect to the end interface of each brand of collaborative robot through a short wire.
(The serial number represent the short wire type.)

Support electric gripper models	UR CB Series	UR E Series	Elite CS Series	SIASUN	Hanwha A Series	ROKAE CR Series	DOBOT CR Series	Jaka
Small current electric gripper (Peak current $\leq$ 0.6A)	C01							
Small current electric gripper (Peak current $<$ 1.5A)		C01	C01	C01	C01			C02
High current electric claw (Peak current $>$ 1.5A)								
In common (Support large and small current electric gripper)						C01	C01	

Dh-robotics' Gripper And Cylinder Communication Converter

The communication within DH-Robotics' Servo Gripper and Servo Electric Cylinder defaults to Modbus RTU (RS485) and a small number of I/O(2 inputs 2 outputs). If customers choose other communication converter, they will need to use the communication converter. The following communication converter are available for selection:

	communication converter Name	Ordering Model
	EtherCAT 1-1	M2E-B1-1
	EtherCAT 1-4	M2E-B1-4
	EtherCAT to I/O 1-More	Please contact our technical staff confirm the specific parameters
	TCP/IP 1-1	M2T-B1-1-YBT
	PROFINET 1-2	M2P2-B1-2-HJ
	PROFINET 1-11	M2P-B1-11-9
	Modbus RTU (RS485) to USB Converter Module	A801-0036-WG