

PGC-140-50

Electric Collaborative Parallel Gripper



Selection Method

Serie	Gripping Force	Stroke	Brake	Cable Direction	Communication Protocol	Cable Selection	Fingertip Selection	Flange Selection	Robot Cable
PGC	140	50	W	S	M1	L5	J1	F1	00
W With Brake S Side M1 Modbus (RS485)+I/O (NN) M2 Modbus (RS485)+I/O (PP) M3 Modbus (RS485)+I/O (NP) M4 Modbus (RS485)+I/O (PN) LX Without Extend Cable L1 1m Cable L3 3m Cable L5 5m Cable L10 10m Cable J1 Standard Fingertip F1 Standard Flange Table Below									