

PGC-50-35

Electric Collaborative Parallel Gripper



Selection Method

Serie	Gripping Force	Stroke	Brake	Cable Direction	Communication Protocol	Cable Selection	Fingertip Selection	Flange Selection	Robot Cable
PGC	50	35	O	S	M1	L5	J1	F1	00
			O Without Brake	S Side			J1 Standard Fingertip	F1 Standard Flange	Table Below